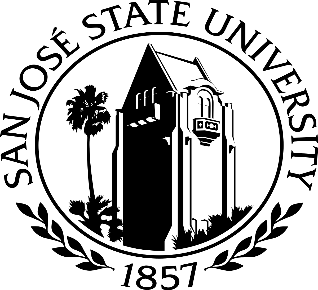
Project Report  
Final Project Report

CMPE 257: Machine Learning  
San Jose State University  
Master of Science in Data Analytics



**Group 8**

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Shubh Johri - 013750672

Selected Machine Learning Algorithm: CNN and Residual Neural Networks

**Link: Google Colaboratory:**

Milestone 1:

<https://colab.research.google.com/drive/1RsvUuIq2oEIHBJ0gHIYIuvorLvGnlHSG>

Milestone 2:

<https://colab.research.google.com/drive/1k_yORhgKA_UJj2sLu65EjLeuT-ytJtOs>

Milestone 3:

<https://colab.research.google.com/drive/1bxt4uQ-1UCLbk1F2DU0M3fylJt93lXja>

<https://colab.research.google.com/drive/1xKD7mBrchr-WfsZV1aloDWbAntDUg0FA>

- This colab file contains CNN for all the 100 trials by removing 2 subclasses from each superclass

<https://colab.research.google.com/drive/1SvmnKzVoWrVzr1ELL5UYIHr4x6v5PDA4>

- Bonus - This colab file contains CNN for all the 100 trials by removing 3 subclasses from each superclass

**Who Did What!**

|  |  |  |
| --- | --- | --- |
| **Milestone 1** | | |
| **What** | **Description** | **Who** |
| Technical | 1. Data Preparation and EDA | Sai Chaitanya |
| 1. Data Validation, Data Preprocessing | Sai Chaitanya, Sameer Rajput |
| 1. Logistic Model | Amar Ippili |
| 1. Random Forest, KNN | Shubh, Aarathi |
| 1. Decision Tress, Naïve Bayes | Shubh, Aarathi |
| 1. SVM, CNN | Divya, Sameer, Chaitanya |
| Presentation | 1. PowerPoint Preparation | Divya, Amar |
| 1. In Class PowerPoint Presentation | Entire Team |
| Documentation | 1. Report Preparation | Sameer, Divya |
| 1. Report Editing | Shubh, Aarathi |

**Who did What!**

|  |  |  |
| --- | --- | --- |
| **Milestone 2** | | |
| **What** | **Description** | **Who** |
| Technical | 1. Data Preparation and EDA | Sai Chaitanya |
| 1. Data Validation, Data Preprocessing | Sai Chaitanya, Sameer Rajput |
| 1. Logistic Model, CNN and Resnet:   bus (vehicle 1)+combinations from vehicle 2  bicycle (vehicle 1)+combinations from vehicle 2  train (vehicle 1)+combinations from vehicle 2  pickup\_truck (vehicle 1)+combinations from vehicle 2  motorcycle (vehicle 1)+combinations from vehicle 2 | Divya  Amar  Shubh  Sameer  Aarathi |
| Presentation | 1. PowerPoint Preparation | Aarathi, Divya |
| 1. In Class PowerPoint Presentation | Entire Team |
| Documentation | 1. Report Preparation and Report Editing | Shubh, Amar |

**Who did What!**

|  |  |  |
| --- | --- | --- |
| **Milestone 3 – Final Report** | | |
| **What** | **Description** | **Who** |
| Technical | 1. Data Preparation and EDA | Sai Chaitanya |
| 1. Data Validation, Data Preprocessing | Sai Chaitanya, Sameer Rajput |
| 1. CNN model for 100 pairs and Bonus question | Divya  Amar  Shubh  Sameer  Aarathi |
| Presentation | 1. PowerPoint Preparation | Aarathi, Divya |
| 1. In Class PowerPoint Presentation | Entire Team |
| Documentation | 1. Report Preparation and Report Editing | Shubh, Amar |

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# About the dataset

The CIFAR-100 dataset has 100 classes containing 600 images each. There are 500 training images and 100 testing images per class. The 100 classes in the CIFAR-100 are grouped into 20 super classes. Each image comes with a "fine" label (the class to which it belongs) and a "coarse" label (the superclass to which it belongs) (CIFAR 100 DATASET).

|  |  |
| --- | --- |
| **Super Class** | **Class** |
| Vehicle 1 | Bicycle, Bus, Motorcycle, Pickup truck, Train |
| Vehicle 2 | Rocket, Tank, Tractor, Streetcar, Lawn-mower |

# Problem

Milestone 1: Our goal is to perform a binary classification of images in vehicle 1 and vehicle 2 superclass pairs.

Milestone 2: The main goal of this project milestone is to design algorithms that would be able to predict a sub-class not available during the training stage. 1 subclass hidden from each of the two super classes.

Milestone 3 (Final Report): The main goal of this project is to perform binary classification of images in vehicle 1 and vehicle 2. The robustness of the algorithm is tested against hiding 2 sub-classes image data during the training stage.

# Software and libraries

**Software: Google Colaboratory Environment** (adventuresinmachinelearning, n.d.)

Google colaboratory environment is based on Python Jupyter notebooks which gives the user free access to Tesla K80 GPUs. It provides the ability to experiment with deep learning. To access the environment, you must have a signed in Google Drive account. The .ipynb files that you create will be saved in your Google Drive account. We have signed in using SJSU Email Id to access the environment and work with cifar100 dataset.

Python Libraries: Keras, Sklearn, Numpy, Matplotlib, Pandas, Scipy, Tensorflow

Keras is a high-level neural networks API, written in Python and we are running it on top of TensorFlow, CNTK, or Theano. It supported both convolutional networks and recurrent networks, as well as combinations of the two and ran seamlessly on CPU and GPU. (Keras Documentation, n.d.)

# Data Preparation

**(Milestone 1, Milestone 2 and Milestone 3)**

Cifar 100 dataset consists of train, test and meta data. We loaded them into colaboratory and combined the images(X), coarse labels(Y) (0-19) data into data frame and filtered this data frame on target variable (vehicle1 =18, vehicle2 = 19) as in Figure 1.

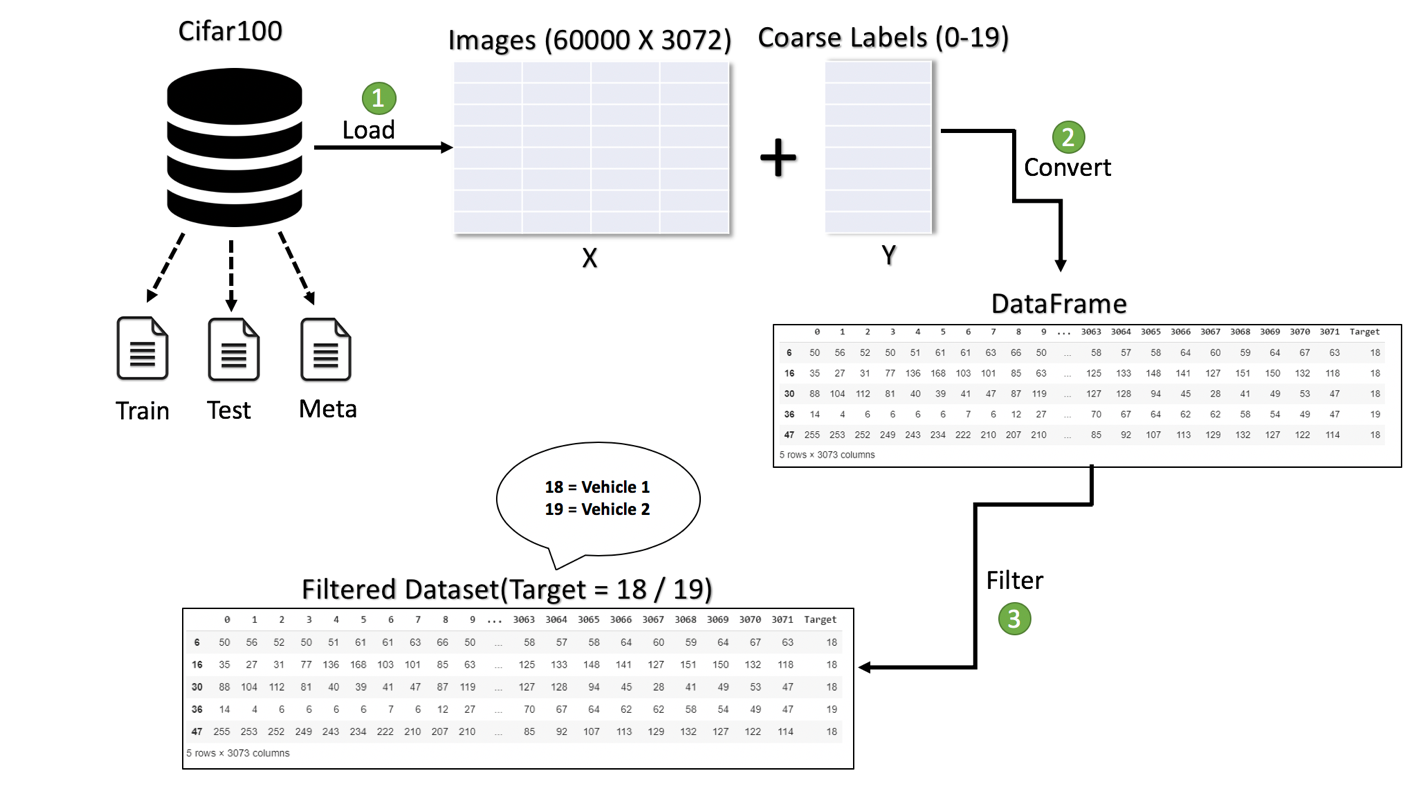


Figure 1

# Data Validation

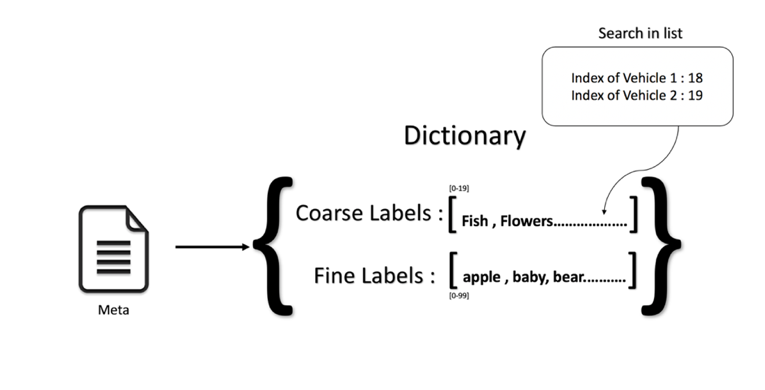


Figure 2

We used the meta data file in cifar 100 which consists of a serialized dictionary object to search for index of vehicle 1, vehicle 2 in the coarse label list as in Figure 2 and validated that 18 corresponds to vehicle 1 and 19 corresponds to vehicle 2 through code and we have crosschecked it by plotting few images from the filtered dataset.

# Data Pre-processing

**(Milestone 1, Milestone 2 and Milestone 3)**

To split the dataset into two sets, one for training and the other for testing, we have split the dataset in an 80–20 ratio such that 80% data is trained.

To reshape our dataset inputs (X\_train and X\_test) to the shape that our model expects when we train the model, we used astype to cast a pandas object into float. And then we used ‘one-hot-encode’ on our target variable using get\_dummies to convert categorical variable into dummy variables and to\_categorical to convert a class vector (integers) to binary class matrix. This means that a column will be created for each output category and a binary variable is inputted for each category.

**(Milestone 2)**

Selection Of one sub- class from each superclass as Testing Data(2 subclasses)

A screenshot of a cell phone

Description automatically generated

Figure 3

**(Milestone 3)**

Selection Of two sub- classes from each superclass as Testing Data(4 subclasses)

A screenshot of a cell phone

Description automatically generated

Figure 4

# Machine Learning Algorithms

**(Milestone 1)**

## 7.1 Logistic Regression

**Accuracy Achieved**: 60.08%

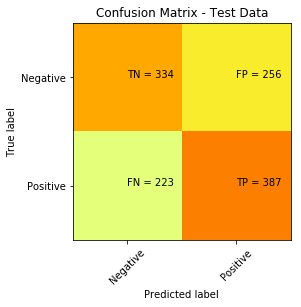


Figure 5

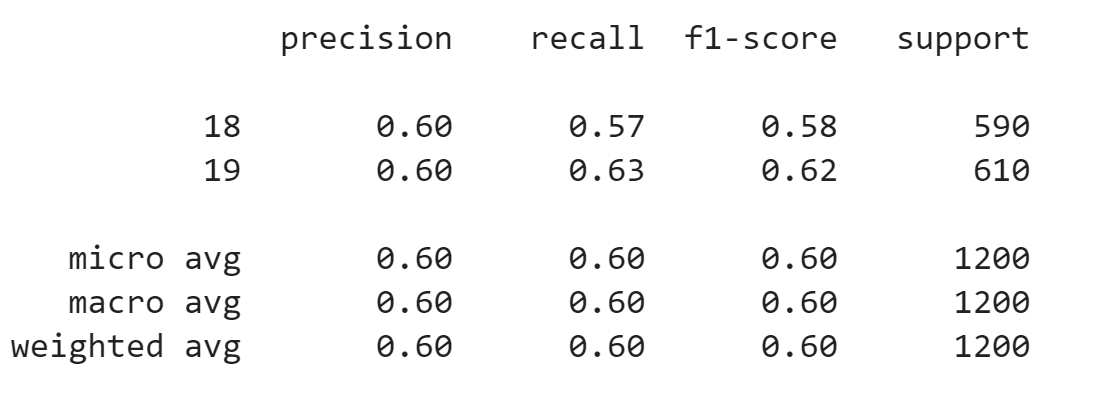


Figure 6

7.2 KNN:

**Accuracy Achieved**: 61.66%

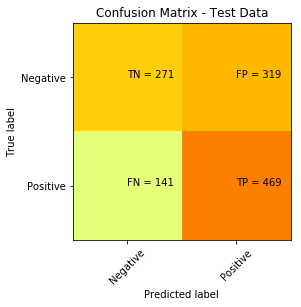


Figure 7

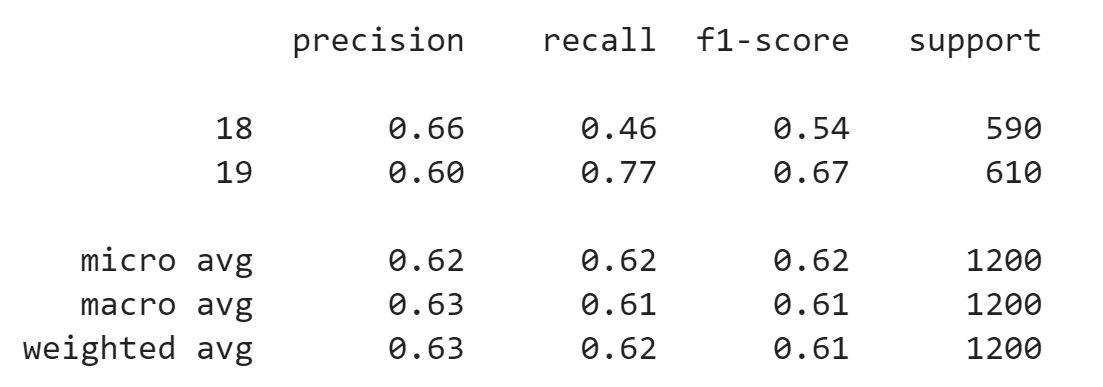


Figure 8

7.3 Naïve Bayes:

**Accuracy achieved:** 55.83%



|  |  |
| --- | --- |
| Figure 9    Figure 10 |  |
|  |  |

7.4 Random Forests:

**Accuracy achieved:** 69.83%

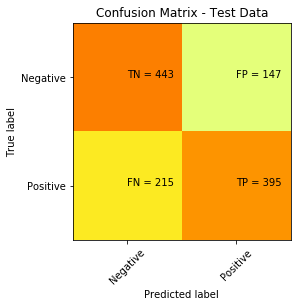


Figure 11

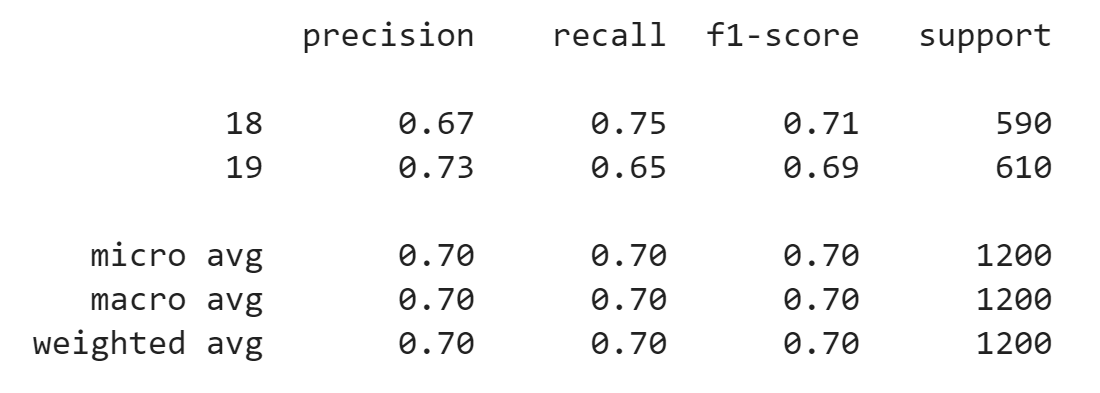


Figure 12

7.5 Decision Tree Classifier:

**Accuracy achieved:** 58.16%

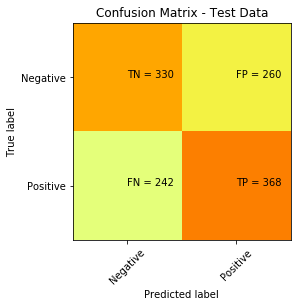


Figure 13

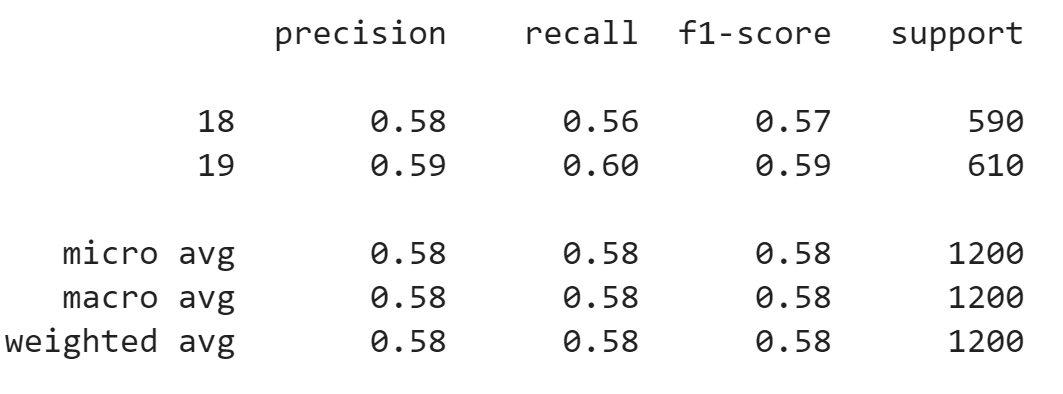


Figure 14

## 7.6 SVM:

**Accuracy achieved:** 68.88%

Confusion Matrix – Test Data

|  |  |  |
| --- | --- | --- |
| **Predicated Label** | **Negative** | **Positive** |
| **True Label** |
| **Negative** | TN = 696 | FP = 281 |
| **Positive** | FN = 335 | TP = 668 |

Figure 15

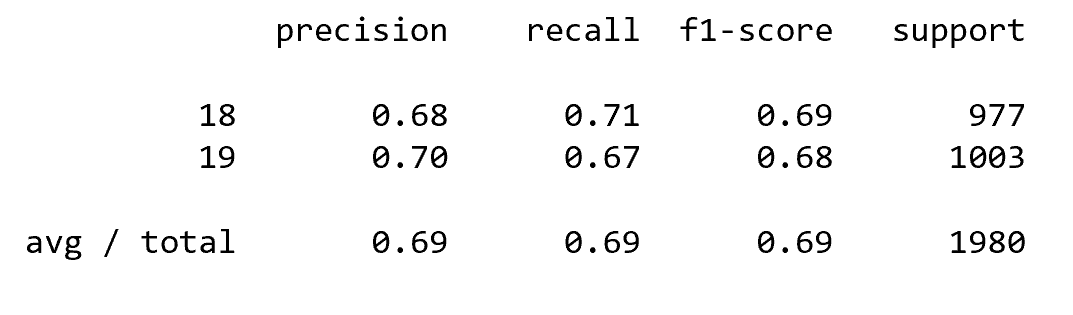


Figure 16

Graphical Representation of Algorithms

A screenshot of a cell phone

Description automatically generated

Figure 17

# Selected Machine Learning Algorithm: CNN

## 8.1 What is CNN?

A Convolutional Neural Network (ConvNet/CNN) is a Deep Learning algorithm which can take in an input image, assign importance (learnable weights and biases) to various aspects/objects in the image and be able to differentiate one from the other. While in primitive methods filters are hand-engineered, with enough training, ConvNets have the ability to learn these filters/characteristics. (Towards DataScience, n.d.)

Our CNN model runs with 200 epochs and batch size of 128 with steps per epoch as 18 having MaxPool and using dropout and image augmentation we tried to prevent overfitting of our model with a learning rate which is neither too high nor too low. (Towards DataScience, n.d.)



Figure 18

## 8.2 Why is CNN better than other algorithms?

The goal of CNN is to reduce the images into a form which is easier to process without losing features which are critical for getting a good prediction. This means that useful attributes from an already trained CNN can be extracted with its trained weights by feeding data on each level and tune the CNN a bit for the specific task.

**Accuracy achieved**: 83.67%

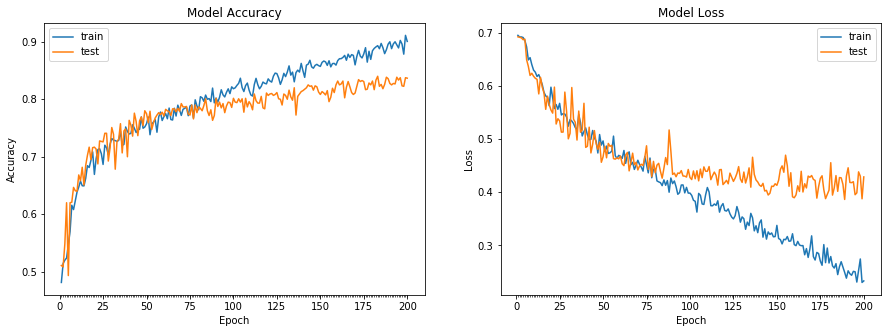


Figure 19

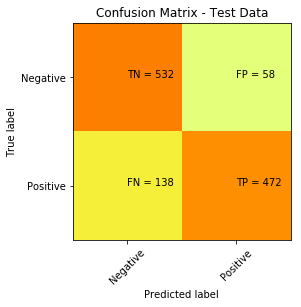


Figure 20

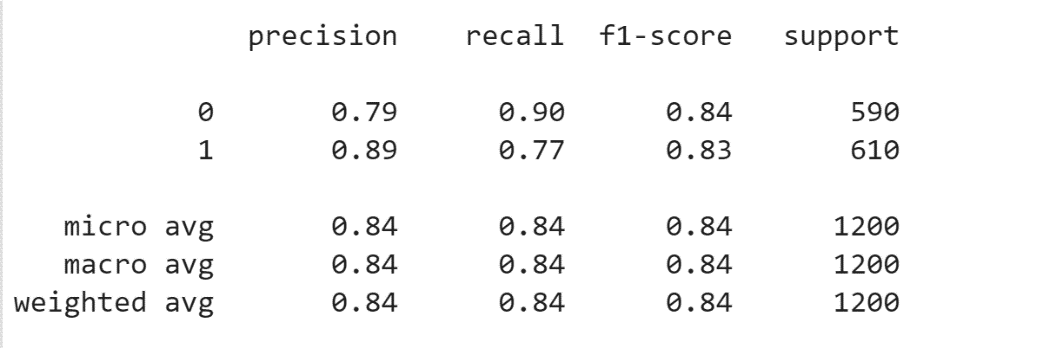
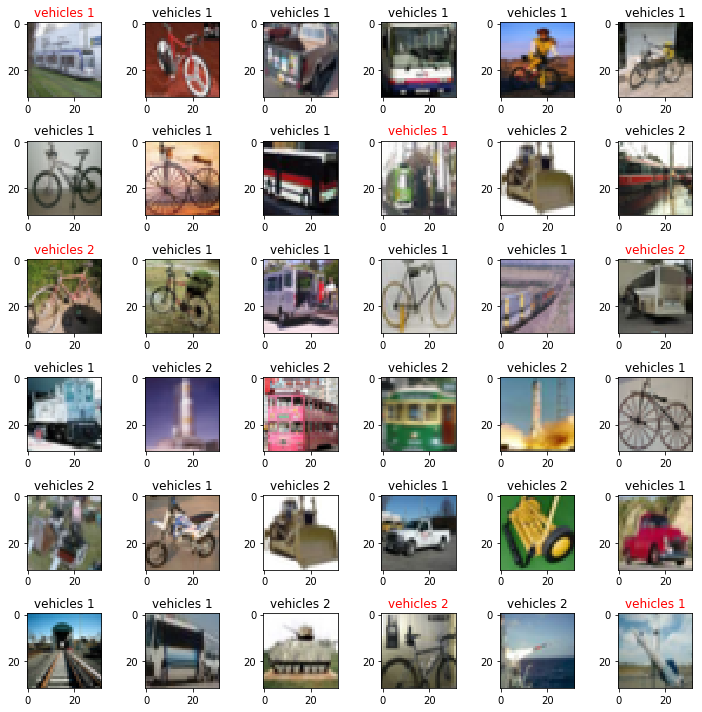


Figure 21

Output



*Figure 22*

**(Milestone 2)**

Less Accuracies from Model in Milestone 1 made us work on one of the classic networks- Resnet.

## What is Resnet?

Residual Networks makes it possible to train up to hundreds or thousands of layers and still achieve compelling performance which can be used as a backbone for many computer vision tasks.

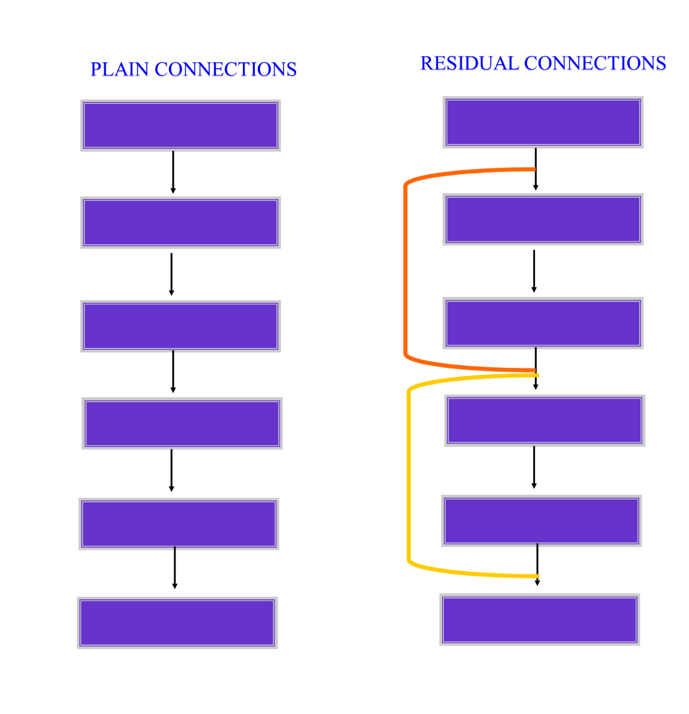


Figure 23

The Resnet in milestone 2 comprises of 29 layers using Batch normalization as a technique for preventing overfitting and understanding concept of dynamic learning rates where callbacks ReduceLROnPlateau in (keras) function was applied at given stages of the training procedure such that learning rate can be reduced when a metric has stopped improving. Keeping parameter patience=5, number of epochs can be decided. Resnet also helps in preserving the problem of vanishing gradient and regularizer kernel is used as well.

**Selected Pair:**

We have selected motorcycle from vehicle1 and lawn\_mower from vehicle2 as they closely resemble cycle, streetcar of vehicle 1, vehicle 2 respectively and our CNN model should be able to classify them easily even though motorcycle, lawn\_mower is not present in the training dataset.

Summarization Chart for 25 trails:

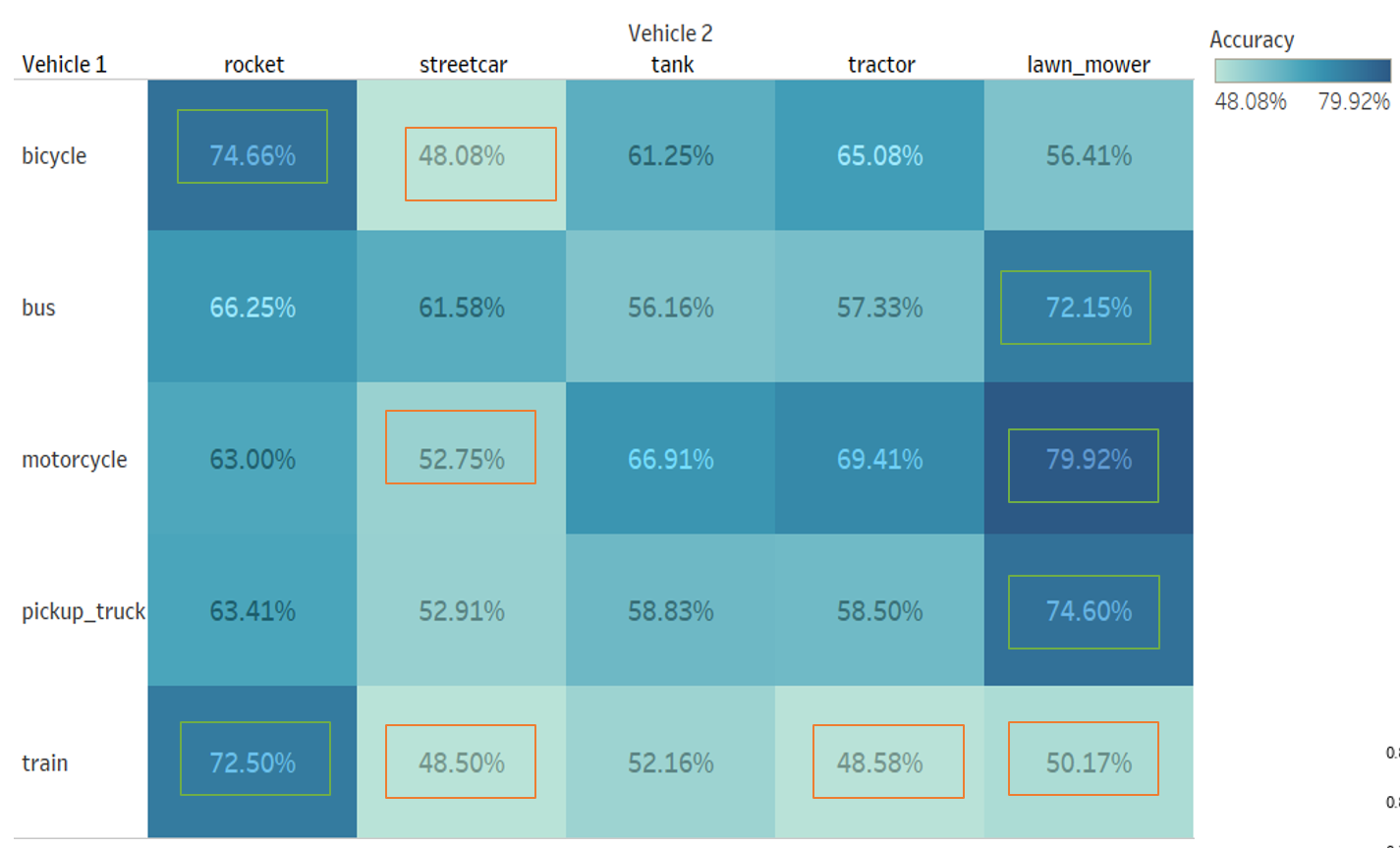


Figure 24

The best pair is motorcycle (vehicle 1) and lawn\_mower (vehicle 2) with accuracy of 79.92%.

Confusion matrix, ROC curve and Classification report for which is as below:

A screenshot of a cell phone

Description automatically generated

Figure 25

A screenshot of a cell phone

Description automatically generated

Figure 26

A picture containing object

Description automatically generated

Figure 27

**Note:** The model is saved when it reached 79.92% accuracy at 11th epoch automatically and reloaded this saved model to plot the confusion matrix, classification report and ROC curve.

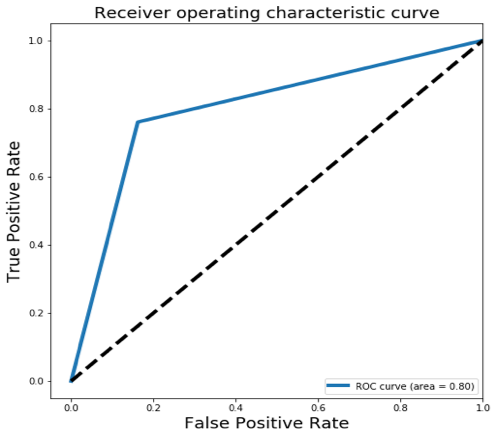


Figure 28

Output

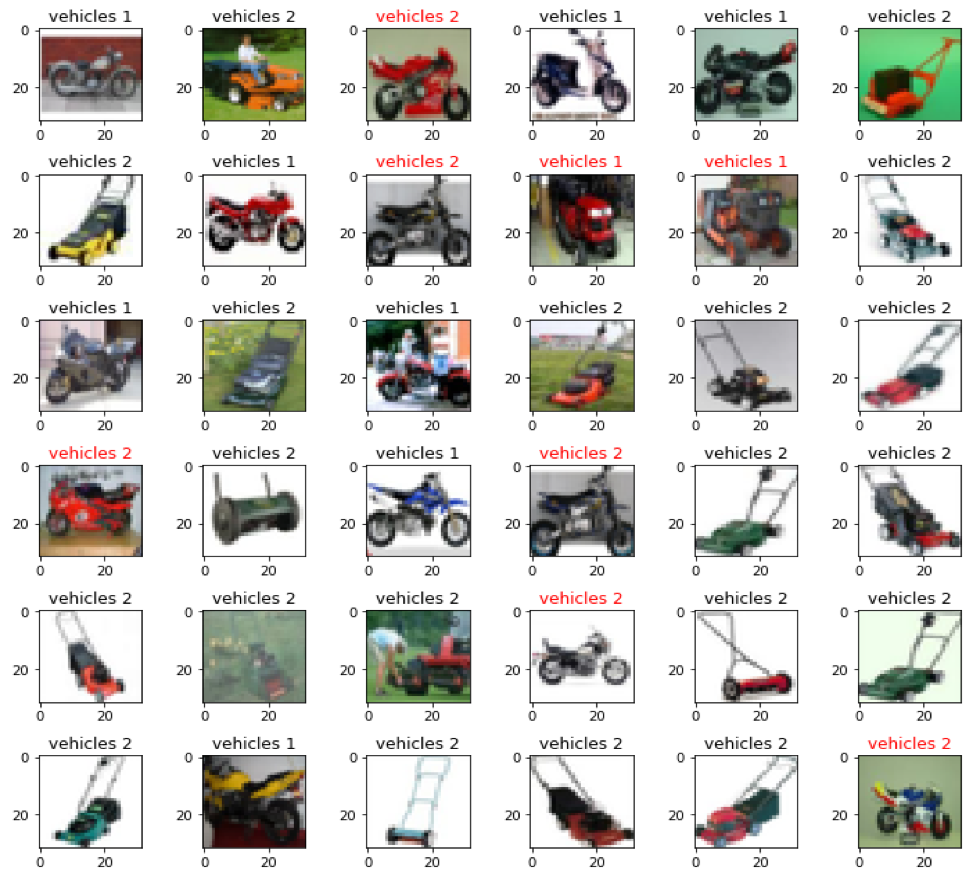
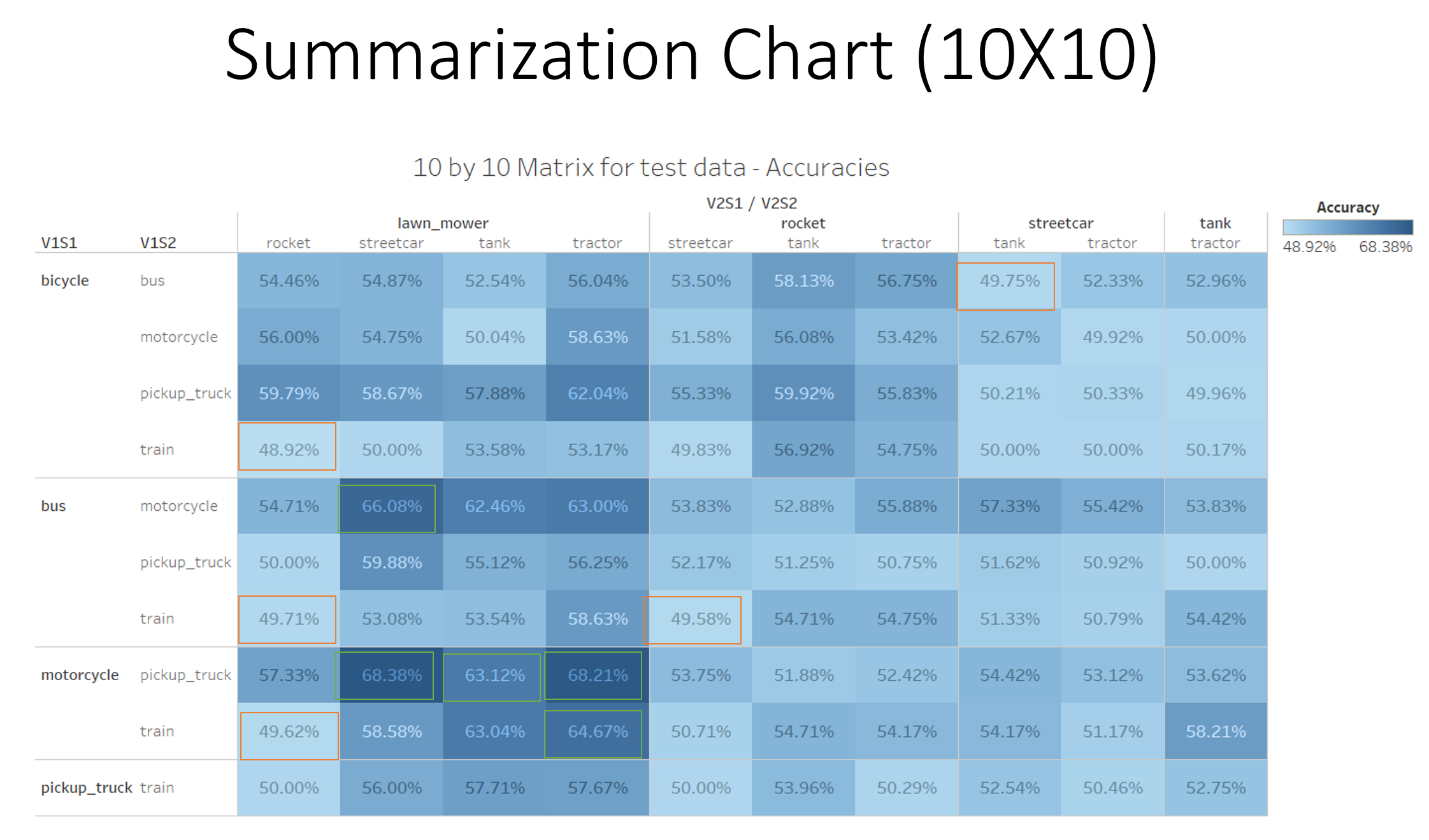


Figure 29

**(Milestone 3)**

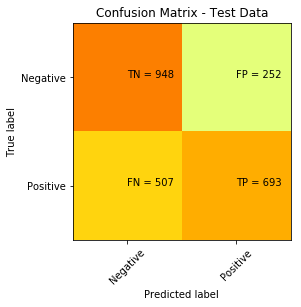
Selected two subclasses from each superclass and used CNN model for classification.



The best combination is motorcycle, pickup truck from vehicle 1 and lawn\_mover, street car from vehicle 2, with the accuracy of 68.38%.

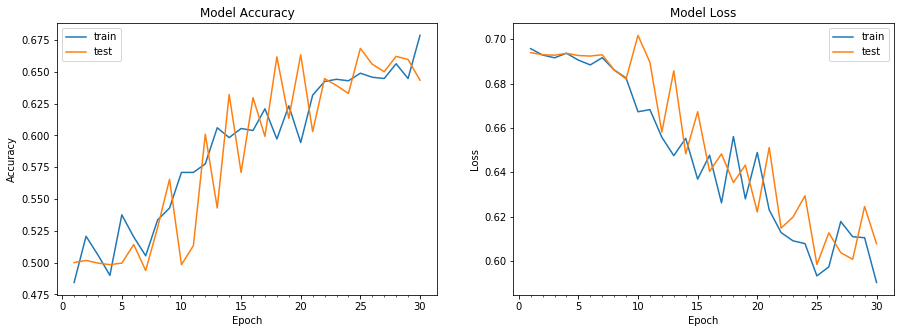
On summarization chart, the best 5 and worst 5 combination accuracies are given in green and red box respectively.

Confusion matrix, ROC curve and Classification report is as below:



![A screenshot of a cell phone

Description automatically generated](data:image/jpeg;base64,/9j/4AAQSkZJRgABAQEAYABgAAD/4REGRXhpZgAATU0AKgAAAAgABAE7AAIAAAAUAAAISodpAAQAAAABAAAIXpydAAEAAAAoAAAQ1uocAAcAAAgMAAAAPgAAAAAc6gAAAAgAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAFNhaSBDaGFpdGFueWEgVG9sZW0AAAWQAwACAAAAFAAAEKyQBAACAAAAFAAAEMCSkQACAAAAAzY4AACSkgACAAAAAzY4AADqHAAHAAAIDAAACKAAAAAAHOoAAAAIAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA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A screenshot of a cell phone

Description automatically generated

Output:

A picture containing wall

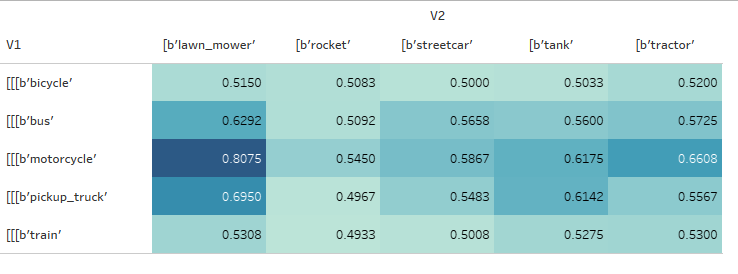
Description automatically generated

**Comparison**

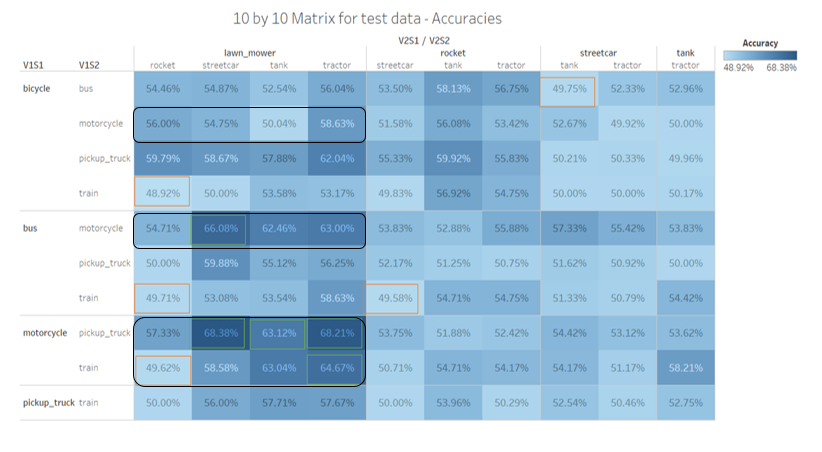
These are the descriptive statistics of the CNN model we used for milestone 2 and milestone 3.

Note: Milestone 2 values are from same model we used for milestone 3 (CNN model).

|  |  |  |
| --- | --- | --- |
|  | Milestone 2 | Milestone 3 |
| Mean | 56.38% | 54.52% |
| Median | 54.50% | 53.79% |
| First Quartile | 50.92% | 50.82% |
| Third Quartile | 58.67% | 56.66% |
| SD | 0.074 | 0.043 |
| Min | 49.33% | 48.92% |
| Max | 80.75% | 68.38% |



By observing the 5x5 chart of predictions on one testing subclass images from each of the two superclasses, “lawn\_mower” has the most resembling features that could be learned by our CNN model through vehicle 2 subclasses and “motorcycle” has the most resembling features that could be learned by our CNN model through vehicle 1. The combinations with these two for predictions on two testing subclass images from each of the two superclasses gave consistent accuracies and the worst combination in 5x5 chart “rocket” has the odd one out features in vehicle 2 which our CNN model didn’t learn and “train” has the odd one out features in vehicle 1 which our CNN model didn’t learn and thus the combinations associated with that pair gave poor accuracies consistently which could be seen in the 10x10 chart below.

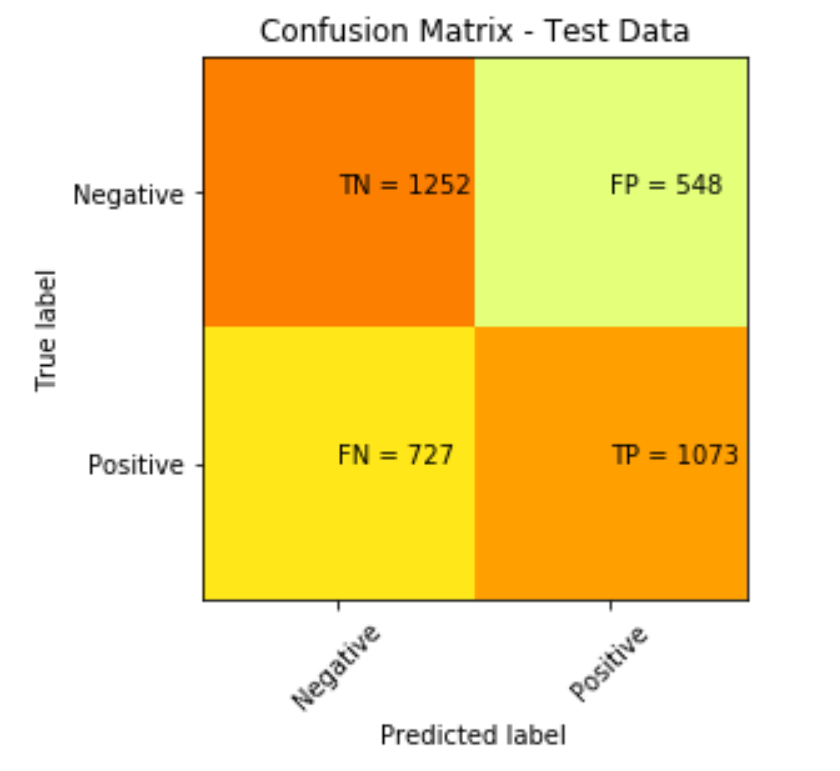


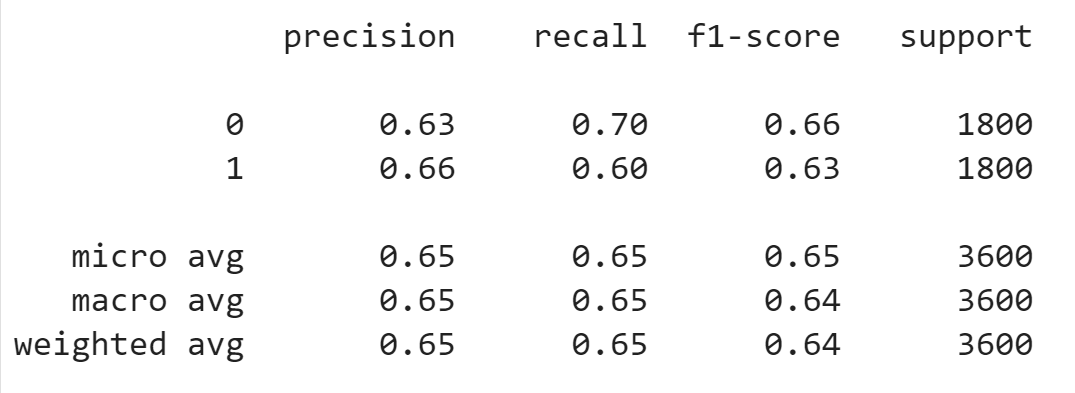
**(Milestone 3 Bonus)**

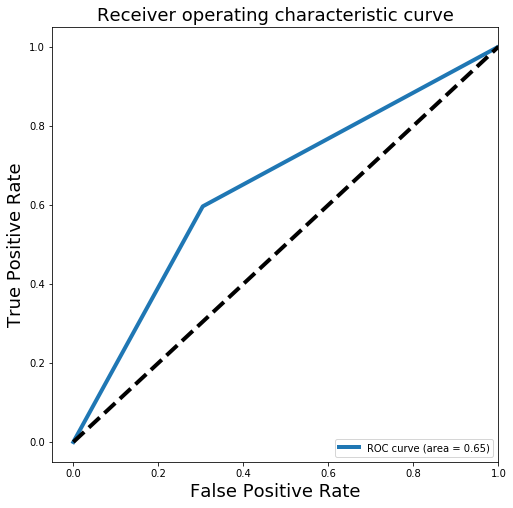
Selected three subclasses from each superclass and used CNN model for classification.

The best combination is bicycle, pickup truck, train from vehicle 1 and rocket, tank, tractor from vehicle 2, with the accuracy of 65.58%.

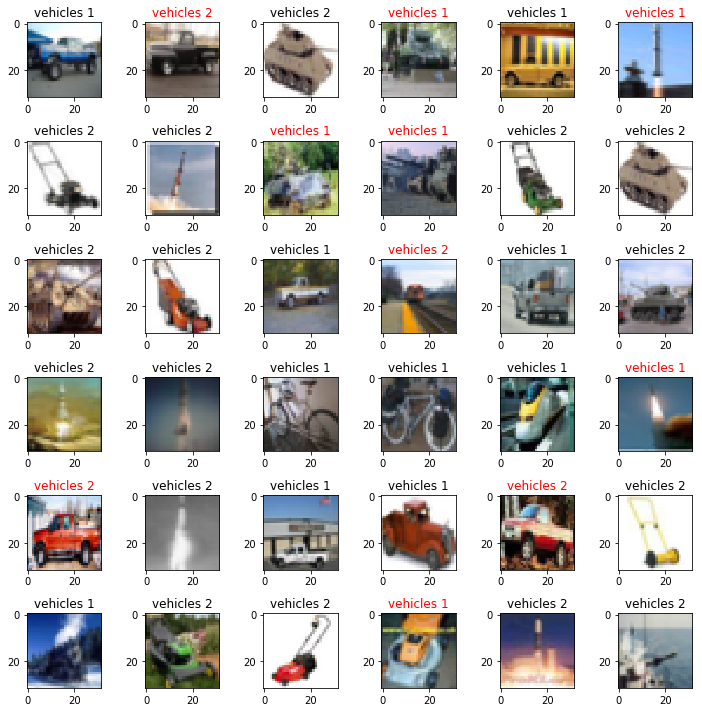
Confusion matrix, ROC curve and Classification report is as below:







Output:



# Conclusion

**(Milestone 1)**

Accuracy, Computation and loss graphs matter. SVM Algorithm took enough time for generating results with accuracy of nearly 70%. Logistic regression and other algorithms did not generate optimal accuracy and the loss graph which made us decide to use CNN for achieving goal of our project.

Initial CNN model did not result in good accuracy and also was overfitted as it was run without using data augmentation. Later we tried to prevent overfitting and also simultaneously increase accuracy by tuning CNN parameters of learning rate, number of epochs, batch size, steps per epoch, using data augmentation and dropout which should be in 20%-50% range. Trying different layer types and number also helped in achieving accuracy.

**(Milestone 2)**

CNN model in milestone 1 did not result in good accuracy. Later we tried to work on one of the classic networks- Resnet. Batch normalization layer prevent overfitting and also simultaneously increased accuracy by tuning CNN parameters of dynamic learning rate (using callbacks), number of epochs, batch size, steps per epoch. Trying “more number of hidden layers, better the accuracy” we used 29 layers which helped in achieving accuracy but loss graph after 15 epochs was not optimal.

**(Milestone 3)**

Data Preprocessing plays an important role as desired level of accuracy cannot be achieved if any data inputs are missing. Several machine learning algorithms are there but not necessarily every algorithm leads to attainment of desired results. CNN worked well when compared with other algorithms like logistic, Naïve Bayes, SVM etc. to attain the objective of image classification. Experimenting with different hyper parameters and their effects gave us practical knowledge and understanding of CNN. Data matters a lot the similarity of features and contrast of features results in varying accuracies.

We tried the CNN model, with loop running 100 times and increase accuracy by tuning parameters of learning rate, number of epochs and batch size. Trying different layer types and number helped us to achieve accuracy of 68.38% for combination of motorcycle, pickup truck from vehicle 1 and lawn\_mover, street car from vehicle 2.

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